





# **Automating Opensim Processing**

## **Automated processing**

- Command line
- API

#### **Command line**

- Execute OpenSim tools from command line
  - All executables that are available in <OpenSim\_Install\_Dir>/bin
    - ik, id, rra, cmc, analyze...
  - Open command window
  - Go to <OpenSim\_Install\_Dir>/bin
  - Run setup file
    - executable –S setup.xml
      - e.g. ik -S setup\_ik.xml
    - Output in command window
      - Add log file
        - » e.g. ik -S setup\_ik.xml > setup\_ik.log
  - Use full paths in setup .xml file

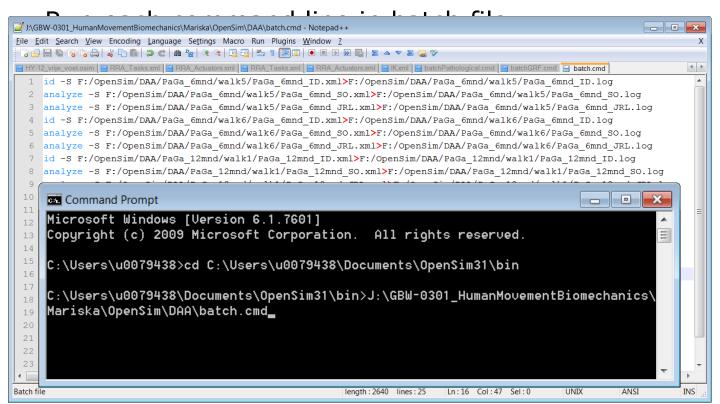
```
Frame 155 (t=4.97): total squared error = 0.0055035, marker error: RMS=0.012 ^ 9141, max=0.0382684 (RTHI)
Frame 156 (t=4.98): total squared error = 0.00546626, marker error: RMS=0.01 28703, max=0.0380896 (RTHI)
InverseKinematicsTool completed 156 frames in 3.071s

IK compute time = 3918ms

C:\Users\u0079438\Documents\OpenSim31\bin>ik -S C:\Users\u0079438\Documents\OpenSimWorkflow\ReferenceSetup\IK.xml > C:\Users\u0079438\Documents\OpenSimWorkflow\ReferenceSetup\IK.xml > C:\Users\u0079438\Documents\OpenSimWorkflow\ReferenceSetup\IK.xml > C:\Users\u0079438\Documents\OpenSimWorkflow\ReferenceSetup\IK.xml > C:\Users\u0079438\Documents\OpenSimWorkflow\ReferenceSetup\IK.log
```

### **Batch processing**

- Command lines in .cmd file
  - e.g. ik -S setup\_ik.xml > setup\_ik.log
    - Write output to log file
  - Combine different analysis
- Run .cmd file from command line



### **OpenSim API**

- Application programming interface
  - Interface between software programs
    - Matlab
    - Python
- Build/adapt models
- Create setup files
- Run analyses

• ...

## **Scripting**

- OpenSim GUI scripting shell
- Matlab
- Python

## **Scripting**

- Matlab
  - Setup Matlab Scripting environment
    - Automated setup from OpenSim 3.2 onward
  - Load OpenSim libraries
  - Import model

```
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                                     straight from the OpenSim distribution
     import org.opensim.modeling.*
     % move to directory where this subject's files are kept
     subjectDir = uigetdir('testData', 'Select the folder that contains the current subject data');
     % Go to the folder in the subject's folder where .trc files are
     trc data folder = uigetdir(subjectDir, 'Select the folder that contains the marker data files in .trc format.');
     % specify where results will be printed.
      results folder = uigetdir(subjectDir, 'Select the folder where the IK Results will be printed.');
     % Get and operate on the files
     % Choose a generic setup file to work from
      [genericSetupForIK,genericSetupPath,FilterIndex] = ...
         uigetfile('*.xml','Pick the a generic setup file to for this subject/model as a basis for changes.');
      ikTool = InverseKinematicsTool([genericSetupPath genericSetupForIK]);
     % Get the model
      [modelFile, modelFilePath, FilterIndex] = ...
          uigetfile('*.osim','Pick the the model file to be used.');
      model = Model([modelFilePath modelFile])
      model.initSystem();
      % Tell Tool to use the loaded model
      ikTool.setModel(model);
59 -
     trialsForIK = dir(fullfile(trc data folder, '*.trc'));
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```

#### **Useful recourses**

- Command line
  - http://simtkconfluence.stanford.edu:8080/display/OpenSim/Command+Line+Utilities
- API
  - <a href="http://simtk-confluence.stanford.edu:8080/display/OpenSim/Introduction+to+the+OpenSim+API">http://simtk-confluence.stanford.edu:8080/display/OpenSim/Introduction+to+the+OpenSim+API</a>
- Scripting
  - http://simtkconfluence.stanford.edu:8080/display/OpenSim/Scripting
  - http://simtkconfluence.stanford.edu:8080/display/OpenSim/Common+Scr ipting+Commands
- Doxygen (documentation of classes and methods)
  - https://simtk.org/api\_docs/opensim/api\_docs32/
- Example scripts
  - Installed with OpenSim
    - <OpenSim\_Install\_Dir>/Scripts